Specifications



## variable speed drive, Altivar Machine ATV320, 2.2kW, 380 to 500V, 3 phases, book

ATV320U22N4B

#### Main

Range Of Product	Altivar Machine ATV320
Product Or Component Type	Variable speed drive
Product Specific Application	Complex machines
Variant	Standard version
Format Of The Drive	Book
Mounting Mode	Cabinet mount
Communication Port Protocol	Modbus serial CANopen
Option Card	Communication module, CANopen Communication module, EtherCAT Communication module, Profibus DP V1 Communication module, PROFINET Communication module, Ethernet Powerlink Communication module, EtherNet/IP Communication module, DeviceNet
[Us] Rated Supply Voltage	380500 V - 1510 %
Nominal Output Current	5.5 A
Motor Power Kw	2.2 kW for heavy duty
Emc Filter	Class C2 EMC filter integrated
Ip Degree Of Protection	IP20

### Complementary

Discrete Input Number	7
Discrete Input Type	STO safe torque off, 24 V DC, impedance: 1.5 kOhm DI1DI6 logic inputs, 24 V DC (30 V) DI5 programmable as pulse input: 030 kHz, 24 V DC (30 V)
Discrete Input Logic	Positive logic (source) Negative logic (sink)
Discrete Output Number	3
Discrete Output Type	Open collector DQ+ 01 kHz 30 V DC 100 mA Open collector DQ- 01 kHz 30 V DC 100 mA
Analogue Input Number	3
Analogue Input Type	Al1 voltage: 010 V DC, impedance: 30 kOhm, resolution 10 bits Al2 bipolar differential voltage: +/- 10 V DC, impedance: 30 kOhm, resolution 10 bits Al3 current: 020 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration), impedance: 250 Ohm, resolution 10 bits
Analogue Output Number	1

are-configurable current AQ1: 020 mA impedance 800 Ohm, resolution 10 are-configurable voltage AQ1: 010 V DC impedance 470 Ohm, resolution 10 gurable relay logic R1A 1 NO electrical durability 100000 cycles gurable relay logic R1B 1 NC electrical durability 100000 cycles gurable relay logic R1C gurable relay logic R2A 1 NO electrical durability 100000 cycles gurable relay logic R2C output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at 250 V AC output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at 30 V DC output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi = 0.4 and L/R = 7 A at 250 V AC output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi = 0.4 and L/R = 7 A at 30 V DC output R2A, R2C on resistive load, cos phi = 1: 5 A at 250 V AC output R2A, R2C on resistive load, cos phi = 1: 5 A at 30 V DC output R2A, R2C on resistive load, cos phi = 1: 5 A at 30 V DC output R1A, R1B, R1C, R2A, R2C: 5 mA at 24 V DC CANopen
gurable relay logic R1B 1 NC electrical durability 100000 cycles gurable relay logic R1C gurable relay logic R2A 1 NO electrical durability 100000 cycles gurable relay logic R2C output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at 250 V AC output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at 30 V DC output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi = 0.4 and L/R = 7 A at 250 V AC output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi = 0.4 and L/R = 7 A at 30 V DC output R2A, R2C on resistive load, cos phi = 1: 5 A at 250 V AC output R2A, R2C on resistive load, cos phi = 1: 5 A at 250 V AC output R2A, R2C on resistive load, cos phi = 1: 5 A at 250 V AC output R2A, R2C on resistive load, cos phi = 1: 5 A at 30 V DC output R1A, R1B, R1C, R2A, R2C: 5 mA at 24 V DC CANopen
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output R1A, R1B, R1C, R2A, R2C: 5 mA at 24 V DC CANopen ge/frequency ratio, 5 points rector control without sensor, standard
ge/frequency ratio, 5 points vector control without sensor, standard
vector control without sensor, standard
vector control without sensor, standard
rector control without sensor - Energy Saving ge/frequency ratio, 2 points
r control without sensor
200 % of nominal motor torque
kHz
r o switching eration/deceleration ramp adaptation eration/deceleration automatic stop with DC injection
natic whatever the load table 0300 % vailable in voltage/frequency ratio (2 or 5 points)
kHz adjustable kHz with derating factor
Cinjection
at 380 V (heavy duty) at 500 V (heavy duty)
/A at 500 V (heavy duty)
0 Hz
74.0 W at 380 V, switching frequency 4 kHz

False
False
False
False
False
True
False
True
False
False
Input phase breaks: drive Overcurrent between output phases and earth: drive Overheating protection: drive Short-circuit between motor phases: drive Thermal protection: drive
60 mm
325.0 mm
245.0 mm

### Environment

Operating Position	Vertical +/- 10 degree
Product Certifications	CE
	ATEX
	NOM
	GOST
	EAC
	RCM
	KC
Marking	CE
	ATEX
	UL
	CSA
	EAC
	RCM
Standards	IEC 61800-5-1
Electromagnetic Compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4
	1.2/50 μs - 8/20 μs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11
Environmental Class (During Operation)	Class 3C3 according to IEC 60721-3-3 Class 3S2 according to IEC 60721-3-3
Maximum Acceleration Under Shock Impact (During Operation)	150 m/s² at 11 ms
Maximum Acceleration Under Vibrational Stress (During Operation)	10 m/s² at 13200 Hz
Maximum Deflection Under Vibratory Load (During Operation)	1.5 mm at 213 Hz
Permitted Relative Humidity (During Operation)	Class 3K5 according to EN 60721-3

Volume Of Cooling Air	11.3 m3/h
Overvoltage Category	111
Regulation Loop	Adjustable PID regulator
Speed Accuracy	+/- 10 % of nominal slip 0.2 Tn to Tn
Pollution Degree	2
Ambient Air Transport Temperature	-2570 °C
Ambient Air Temperature For Operation	-1050 °C without derating 5060 °C with derating factor
Ambient Air Temperature For Storage	-2570 °C

## **Packing Units**

Unit Type Of Package 1	PCE
Number Of Units In Package 1	1
Package 1 Height	9.600 cm
Package 1 Width	27.500 cm
Package 1 Length	32.500 cm
Package 1 Weight	2.757 kg
Unit Type Of Package 2	S06
Number Of Units In Package 2	20
Package 2 Height	75.000 cm
Package 2 Width	60.000 cm
Package 2 Length	80.000 cm
Package 2 Weight	68.760 kg

### Sustainability

**Green Premium<sup>TM</sup> label** is Schneider Electric's commitment to delivering products with best-inclass environmental performance. Green Premium promises compliance with the latest regulations, transparency on environmental impacts, as well as circular and low-CO<sub>2</sub> products.

**Guide to assessing product sustainability** is a white paper that clarifies global eco-label standards and how to interpret environmental declarations.

Learn more about Green Premium >

Guide to assess a product's sustainability >



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Transparency RoHS/REACh

#### **Resource performance**

Upgraded Components Available

#### Well-being performance

Mercury Free

Rohs Exemption Information Yes

### **Certifications & Standards**

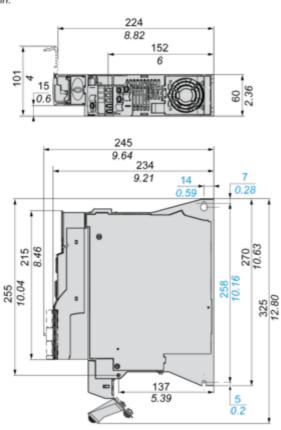
Reach Regulation	REACh Declaration
Eu Rohs Directive	Pro-active compliance (Product out of EU RoHS legal scope)
China Rohs Regulation	China RoHS declaration
Environmental Disclosure	Product Environmental Profile
Weee	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins
weee Circularity Profile	

**Dimensions Drawings** 

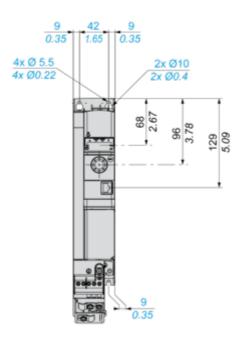
Dimensions

Bottom, Right and Front View



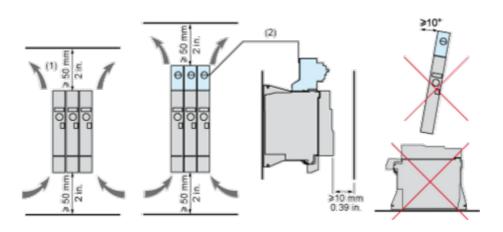






Mounting and Clearance

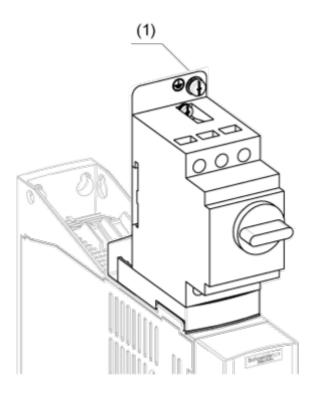
#### Mounting and Clearance



(1) Minimum value corresponding to thermal constraints.(2) Optional GV2 circuit-breaker

Option: Protection Device, GV2 circuit-breaker

**NOTE:** The product overall height dimension, including GV2 adapter and EMC plate mounted, becomes 424 mm (16.7 in.) instead of 325 mm (12.80 in.)



(1) Ground screw (HS type 2 - 5x12)

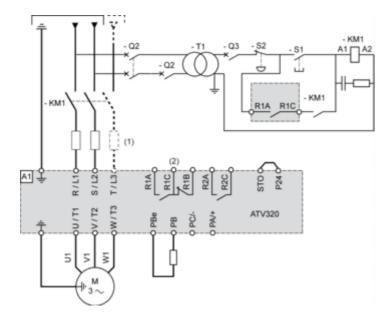
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#### Connections and Schema

#### **Connection Diagrams**

#### **Diagram with Line Contactor**

Connection diagrams conforming to standards ISO13849 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.

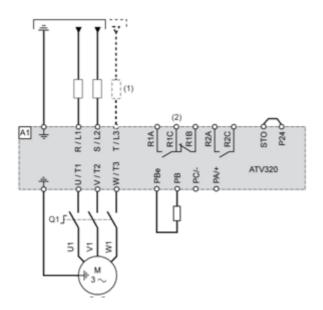


(1) Line choke (if used)

(2) Fault relay contacts, for remote signaling of drive status

#### **Diagram with Switch Disconnect**

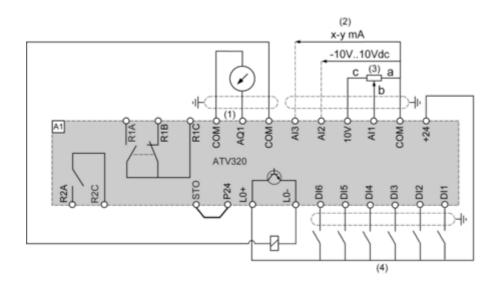
Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.



(1) Line choke (if used)

(2) Fault relay contacts, for remote signaling of drive status

#### Control Connection Diagram in Source Mode



(1) Analog output

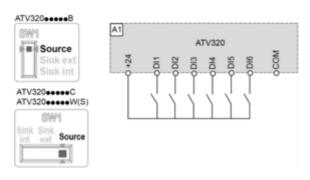
- (2) Analog inputs
- (3) Reference potentiometer (10 kOhm maxi)
- (4) Digital inputs

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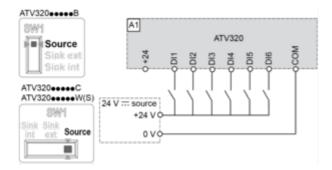
#### **Digital Inputs Wiring**

The logic input switch (SW1) is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

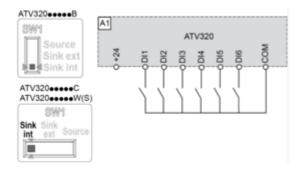
Switch SW1 set to "Source" position and use of the output power supply for the DIs.



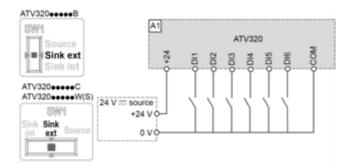
Switch SW1 set to "Source" position and use of an external power supply for the DIs.



Switch SW1 set to "Sink Int" position and use of the output power supply for the DIs.



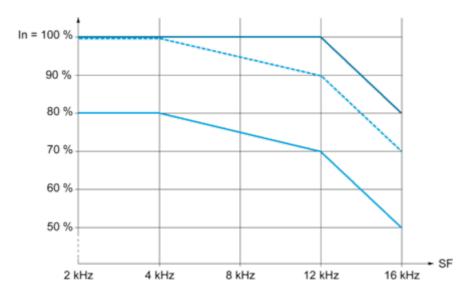
Switch SW1 set to "Sink Ext" position and use of an external power supply for the DIs.



#### Performance Curves

#### **Derating Curves**

Derating curve for the nominal drive current (In) as a function of temperature and switching frequency (SF).



40 °C (104 °F) - Mounting type A, B and C 50 °C (122 °F) - Mounting type A, B and C 60 °C (140 °F) - Mounting type B and C

In : Nominal Drive Current

SF : Switching Frequency