

variable speed drive, Altivar Machine ATV320, 5.5kW, 380 to 500V, 3 phases, book

ATV320U55N4B

Main

PV1 owerlink

Complementary

Discrete Input Number	7
Discrete Input Type	STO safe torque off, 24 V DC, impedance: 1.5 kOhm DI1DI6 logic inputs, 24 V DC (30 V) DI5 programmable as pulse input: 030 kHz, 24 V DC (30 V)
Discrete Input Logic	Positive logic (source) Negative logic (sink)
Discrete Output Number	3
Discrete Output Type	Open collector DQ+ 01 kHz 30 V DC 100 mA Open collector DQ- 01 kHz 30 V DC 100 mA
Analogue Input Number	3
Analogue Input Type	Al1 voltage: 010 V DC, impedance: 30 kOhm, resolution 10 bits Al2 bipolar differential voltage: +/- 10 V DC, impedance: 30 kOhm, resolution 10 bits Al3 current: 020 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration), impedance: 250 Ohm, resolution 10 bits
Analogue Output Number	1

Life Is On Schneider May 3, 2024

Analogue Output Type Software-configurable current AQ1: 020 mA impedance 800 Ohbits Software-configurable voltage AQ1: 010 V DC impedance 470 Cbits Relay Output Type Configurable relay logic R1A 1 NO electrical durability 100000 cyc Configurable relay logic R1B 1 NC electrical durability 100000 cyc Configurable relay logic R1C Configurable relay logic R2A 1 NO electrical durability 100000 cyc Configurable relay logic R2C Maximum Switching Current Relay output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at Relay output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at Relay output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi ms: 2 A at 250 V AC Relay output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi ms: 2 A at 30 V DC Relay output R2A, R2C on resistive load, cos phi = 1: 5 A at 250 V Relay output R2A, R2C on resistive load, cos phi = 1: 5 A at 30 V Minimum Switching Current Relay output R1A, R1B, R1C, R2A, R2C: 5 mA at 24 V DC Method Of Access Slave CANopen True	Dhm, resolution 10 cles cles cles cles cles cles cles cle
Configurable relay logic R1B 1 NC electrical durability 100000 cyc Configurable relay logic R1C Configurable relay logic R2A 1 NO electrical durability 100000 cyc Configurable relay logic R2C Maximum Switching Current Relay output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at Relay output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at Relay output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi ms: 2 A at 250 V AC Relay output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi ms: 2 A at 30 V DC Relay output R2A, R2C on resistive load, cos phi = 1: 5 A at 250 V Relay output R2A, R2C on resistive load, cos phi = 1: 5 A at 30 V Minimum Switching Current Relay output R1A, R1B, R1C, R2A, R2C: 5 mA at 24 V DC Method Of Access Slave CANopen	2250 V AC 30 V DC ni = 0.4 and L/R = 7 ni = 0.4 and L/R = 7
Configurable relay logic R2A 1 NO electrical durability 100000 cyc. Configurable relay logic R2C Maximum Switching Current Relay output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at Relay output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at Relay output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi ms: 2 A at 250 V AC Relay output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi ms: 2 A at 30 V DC Relay output R2A, R2C on resistive load, cos phi = 1: 5 A at 250 V Relay output R2A, R2C on resistive load, cos phi = 1: 5 A at 30 V DC Relay output R2A, R2C on resistive load, cos phi = 1: 5 A at 30 V Minimum Switching Current Relay output R1A, R1B, R1C, R2A, R2C: 5 mA at 24 V DC Method Of Access Slave CANopen	250 V AC 30 V DC ni = 0.4 and L/R = 7 ni = 0.4 and L/R = 7
Relay output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at Relay output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi ms: 2 A at 250 V AC Relay output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi ms: 2 A at 30 V DC Relay output R2A, R2C on resistive load, cos phi = 1: 5 A at 250 V Relay output R2A, R2C on resistive load, cos phi = 1: 5 A at 30 V Minimum Switching Current Relay output R1A, R1B, R1C, R2A, R2C: 5 mA at 24 V DC Method Of Access Slave CANopen	30 V DC ni = 0.4 and L/R = 7 ni = 0.4 and L/R = 7
Method Of Access Slave CANopen	
Sale of Hopen	
4 Quadrant Operation Possible True	
Asynchronous Motor Control Profile Voltage/frequency ratio, 5 points Flux vector control without sensor, standard Voltage/frequency ratio - Energy Saving, quadratic U/f Flux vector control without sensor - Energy Saving Voltage/frequency ratio, 2 points	
Synchronous Motor Control Vector control without sensor Profile	
Transient Overtorque 170200 % of nominal motor torque	
Maximum Output Frequency 0.599 kHz	
Acceleration And Deceleration Ramps Linear U S CUS Ramp switching Acceleration/deceleration ramp adaptation Acceleration/deceleration automatic stop with DC injection	
Motor Slip Compensation Automatic whatever the load Adjustable 0300 % Not available in voltage/frequency ratio (2 or 5 points)	
Switching Frequency 216 kHz adjustable 416 kHz with derating factor	
Nominal Switching Frequency 4 kHz	
Braking To Standstill By DC injection	
Brake Chopper Integrated True	
Line Current 20.7 A at 380 V (heavy duty) 14.5 A at 500 V (heavy duty)	
Maximum Input Current 20.7 A	
Maximum Output Voltage 500 V	
Apparent Power 12.6 kVA at 500 V (heavy duty)	
Network Frequency 5060 Hz	
Relative Symmetric Network 5 % Frequency Tolerance	
Prospective Line Isc 22 kA	
Base Load Current At High 14.3 A Overload	
Power Dissipation In W Fan: 195.0 W at 380 V, switching frequency 4 kHz	
With Safety Function Safely True Limited Speed (SIs)	

With Safety Function Safe Brake Management (Sbc/Sbt)	False
With Safety Function Safe Operating Stop (Sos)	False
With Safety Function Safe Position (Sp)	False
With Safety Function Safe Programmable Logic	False
With Safety Function Safe Speed Monitor (Ssm)	False
With Safety Function Safe Stop 1 (Ss1)	True
With Sft Fct Safe Stop 2 (Ss2)	False
With Safety Function Safe Torque Off (Sto)	True
With Safety Function Safely Limited Position (SIp)	False
	False
Limited Position (SIp) With Safety Function Safe	
Limited Position (SIp) With Safety Function Safe Direction (Sdi)	Input phase breaks: drive Overcurrent between output phases and earth: drive Overheating protection: drive Short-circuit between motor phases: drive
Limited Position (SIp) With Safety Function Safe Direction (Sdi) Protection Type	Input phase breaks: drive Overcurrent between output phases and earth: drive Overheating protection: drive Short-circuit between motor phases: drive Thermal protection: drive
Limited Position (SIp) With Safety Function Safe Direction (Sdi) Protection Type Width	Input phase breaks: drive Overcurrent between output phases and earth: drive Overheating protection: drive Short-circuit between motor phases: drive Thermal protection: drive

Environment

Operating Position	Vertical +/- 10 degree
Product Certifications	CE ATEX NOM GOST EAC RCM KC
Marking	CE ATEX UL CSA EAC RCM
Standards	IEC 61800-5-1
Electromagnetic Compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11
Environmental Class (During Operation)	Class 3C3 according to IEC 60721-3-3 Class 3S2 according to IEC 60721-3-3
Maximum Acceleration Under Shock Impact (During Operation)	150 m/s² at 11 ms
Maximum Acceleration Under Vibrational Stress (During Operation)	10 m/s² at 13200 Hz
Maximum Deflection Under Vibratory Load (During Operation)	1.5 mm at 213 Hz
Permitted Relative Humidity (During Operation)	Class 3K5 according to EN 60721-3

Volume Of Cooling Air	60 m3/h
Overvoltage Category	III
Regulation Loop	Adjustable PID regulator
Speed Accuracy	+/- 10 % of nominal slip 0.2 Tn to Tn
Pollution Degree	2
Ambient Air Transport Temperature	-2570 °C
Ambient Air Temperature For Operation	-1050 °C without derating 5060 °C with derating factor
Ambient Air Temperature For Storage	-2570 °C

Packing Units

Unit Type Of Package 1	PCE
Number Of Units In Package 1	1
Package 1 Height	20.500 cm
Package 1 Width	33.000 cm
Package 1 Length	27.200 cm
Package 1 Weight	5.511 kg
Unit Type Of Package 2	P06
Number Of Units In Package 2	10
Package 2 Height	75.000 cm
Package 2 Width	60.000 cm
Package 2 Length	80.000 cm
Package 2 Weight	68.110 kg

Sustainability

Green PremiumTM label is Schneider Electric's commitment to delivering products with best-inclass environmental performance. Green Premium promises compliance with the latest regulations, transparency on environmental impacts, as well as circular and low-CO₂ products.

Guide to assessing product sustainability is a white paper that clarifies global eco-label standards and how to interpret environmental declarations.

Learn more about Green Premium >

Guide to assess a product's sustainability >





Transparency RoHS/REACh

Resource performance



Upgraded Components Available

Well-being performance



Mercury Free



Rohs Exemption Information

Yes

Certifications & Standards

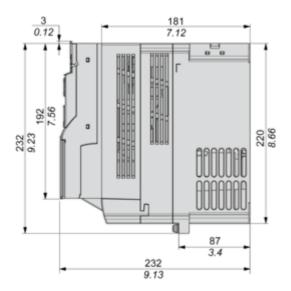
Reach Regulation	REACh Declaration
Eu Rohs Directive	Pro-active compliance (Product out of EU RoHS legal scope)
China Rohs Regulation	China RoHS declaration
Environmental Disclosure	Product Environmental Profile
Weee	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins
Circularity Profile	End of Life Information
California Proposition 65	WARNING: This product can expose you to chemicals including: Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm. For more information go to www.P65Warnings.ca.gov

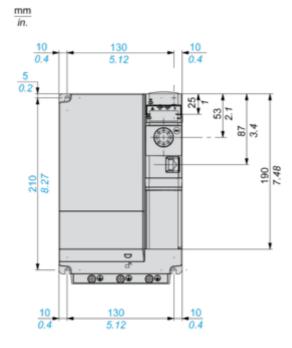
Dimensions Drawings

Dimensions

Right and Front View

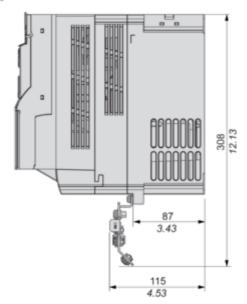
mm in.



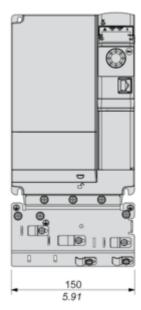


Right and Front View with EMC Plate

mm in.

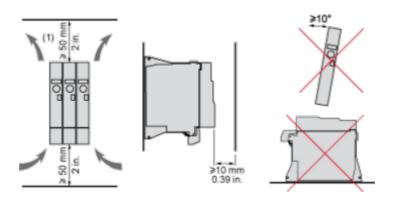


mm in.



Mounting and Clearance

Mounting and Clearance



(1) Minimum value corresponding to thermal constraints.

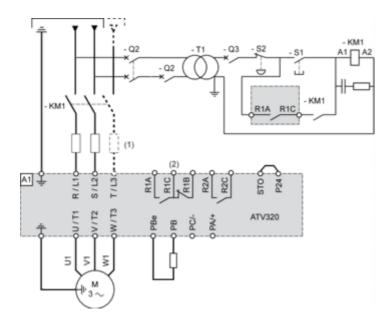
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Connections and Schema

Connection Diagrams

Diagram with Line Contactor

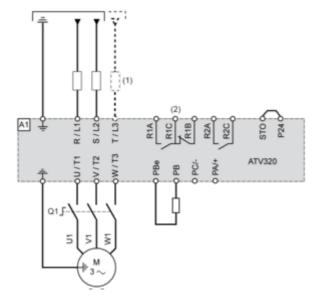
Connection diagrams conforming to standards ISO13849 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.



- (1) Line choke (if used)
- (2) Fault relay contacts, for remote signaling of drive status

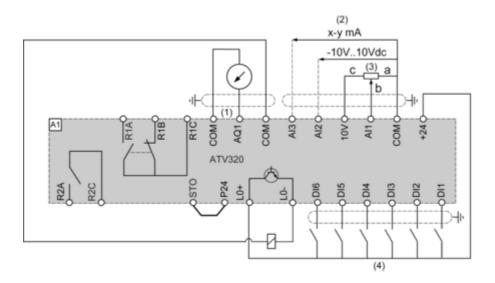
Diagram with Switch Disconnect

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.



- (1) Line choke (if used)
- (2) Fault relay contacts, for remote signaling of drive status

Control Connection Diagram in Source Mode

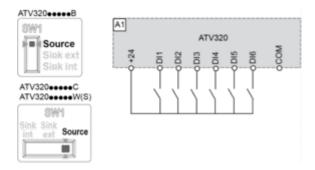


- (1) Analog output
- (2) Analog inputs
- (3) Reference potentiometer (10 kOhm maxi)
- (4) Digital inputs

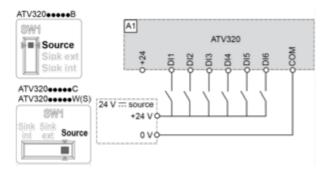
Digital Inputs Wiring

The logic input switch (SW1) is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

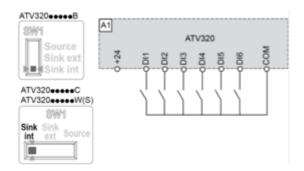
Switch SW1 set to "Source" position and use of the output power supply for the DIs.



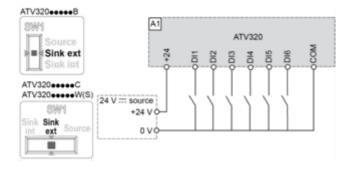
Switch SW1 set to "Source" position and use of an external power supply for the Dls.



Switch SW1 set to "Sink Int" position and use of the output power supply for the DIs.



Switch SW1 set to "Sink Ext" position and use of an external power supply for the Dls.



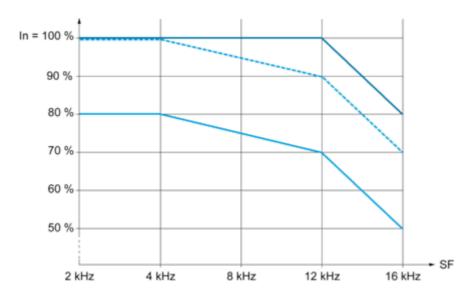
Product data sheet

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Performance Curves

Derating Curves

Derating curve for the nominal drive current (In) as a function of temperature and switching frequency (SF).



40 °C (104 °F) - Mounting type A, B and C 50 °C (122 °F) - Mounting type A, B and C 60 °C (140 °F) - Mounting type B and C

In : Nominal Drive Current
SF : Switching Frequency